

P101



- Non-contacting inductive technology to eliminate wear
- Travel set to customer's requirement
- **Compact and self-contained**
- High durability and reliability
- High accuracy and stability
- Sealing to IP65/IP67 as required

As a leading designer and manufacturer of linear, rotary, tilt and intrinsically safe position sensors, Positek[®] has the expertise to supply a sensor to suit a wide variety of applications.

Our P101 LIPS® (Linear Inductive Position Sensor) is an affordable, durable, high-accuracy position sensor designed for industrial and scientific feedback applications. The unit is highly compact and space-efficient, beina responsive along almost its entire length.

The P101, like all Positek[®] sensors, provides a linear output proportional to travel. Each unit is supplied with the output calibrated to the travel required by the customer, any stroke from 0-5mm to 0-800mm and with full EMC protection built in. The sensor is very robust, the body and push rod being made of stainless steel for long service life and environmental resistance. It is particularly suitable for OEMs seeking good sensor performance for arduous applications such as industrial machinery where cost is important.

Overall performance, repeatability and stability are outstanding over a wide temperature range. The sensor is easy to install with mounting options including M5 rod eye bearings and body clamps. The push rod can be supplied free or captive, with female M5 thread, an M5 rod eye, or Captive push rods can be sprung dome end, loaded, in either direction, on sensors up to The P101 also offers a wide 250mm of travel. range of mechanical and electrical options, environmental sealing is to IP65 or IP67, depending on selected cable or connector options.



SPECIFICATION

Dimensions Body diameter Body length (Axial version) Body length (Radial version) 35 mm calibrated travel + 163 mm calibrated travel + 186 mm calibrated travel + 9 mm, OD 9.5 mm Push rod extension For full mechanical details see drawing P101-11 **Independent Linearity** $\leq \pm 0.25\%$ FSO @ 20°C - up to 450 mm $\leq \pm 0.5\%$ FSO @ 20°C - over 450 mm $\leq \pm 0.1\%$ FSO @ 20°C^{*} available upon request. *Sensors with calibrated travel from 10 mm up to 400 mm. **Temperature Coefficients** < ± 0.01%/°C Gain & < ± 0.01%FS/°C Offset > 10 kHz (-3dB) > 300 Hz (-3dB) 2 wire 4 to 20 mA Frequency response Resolution Infinite < 0.02% FSO Noise **Environmental Temperature Limits** -40°C to +125°C standard -20°C to +85°C buffered -40°C to +125°C Operating Storage IP65/IP67 depending on connector / cable option EN 61000-6-2, EN 61000-6-3 Sealing EMC Performance IEC 68-2-6: 10 g IEC 68-2-29: 40 g 350,000 hrs 40°C Gf

Vibration Shock MTBF **Drawing List**

P101-11 Sensor Outline Drawings, in AutoCAD[®] dwg or dxf format, available on request.

Do you need a position sensor made to order to suit a particular installation requirement or specification? We'll be happy to modify any of our designs to suit your needs please contact us with your requirements.

PM Instrumentation | 59 rue Emile Deschanel | F-92400 Courbevoie | France +33(0)146919332 | contact@pm-instrumentation.com | www.pm-instrumentation.com



P101



LIPS[®] P101 STAND-ALONE LINEAR POSITION SENSOR

Position feedback for industrial and scientific applications

How Positek's PIPS[®] technology eliminates wear for longer life

Positek's **PIPS**[®] technology (Positek Inductive Position Sensor) is a major advance in displacement sensor design. PIPS[®]-based displacement transducers have the simplicity of a potentiometer with the life of an LVDT/RVDT.

PIPS[®] technology combines the best in fundamental inductive principles with advanced micro-electronic integrated circuit technology. A PIPS[®] sensor, based on simple inductive coils using Positek's ASIC control technology, directly measures absolute position giving a DC analogue output signal. Because there is no contact between moving electrical components, reliability is high and wear is eliminated for an exceptionally long life.

PIPS[®] overcomes the drawbacks of LVDT technology – bulky coils, poor length-to-stroke ratio and the need for special magnetic materials. It requires no separate signal conditioning.

Our LIPS[®] range are linear sensors, while RIPS[®] are rotary units and TIPS[®] are for detecting tilt position. Ask us for a full technical explanation of PIPS[®] technology.

We also offer a range of ATEX-qualified intrinsicallysafe sensors.

TABLE OF OPTIONS

CALIBRATED TRAVEL: Factory set to any length from 0-5mm to 0-800mm (e.g. 254mm)

ELECTRICAL INTERFACE OPTIONS

| OUTPUT SIGNAL Standard: | SUPPLY INPUT | OUTPUT LOAD | | | | | |
|---|---|---|--|--|--|--|--|
| 0.5-4.5V dc ratiometric Buffered: | +5V dc nom. \pm 0.5V. | 5kΩ min. | | | | | |
| 0.5-4.5V dc ±5V dc | +24V dc nom. + 9-28V. ±15V dc nom. ± 9-28V. | 5kΩ min. 5kΩ min. | | | | | |
| 0.5-9.5V dc ±10V dc | +24V dc nom. + 13-28V. +15 V dc nom. + 13.5-28V. | $5k\Omega$ min. 5kΩ min. 5kΩ min. | | | | | |
| Supply Current | 10mA typical, 20mA maximum. | | | | | | |
| 4-20mA (2 wire) (3 wire sink) (3 wire source) | +24 V dc nom. + 18-28V. +24 V dc nom. + 13-28V. +24 V dc nom. + 13-28V. | 300Ω @ 24V. 950Ω @ 24V. 300Ω max. | | | | | |
| | | | | | | | |

Axial sensors supplied with access to output 'zero' and 'span' calibration adjustments as standard. No access option available.

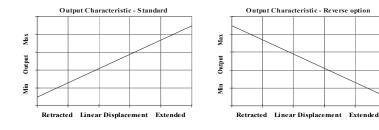
CONNECTOR/CABLE OPTIONS

Connector - Hirschmann GD series Axial, IP65 Connector - Hirschmann ELWIKA 4102 Radial, IP67 Cable with M12 gland or short gland Axial, IP67 Cable with Pg 9 gland Radial, IP67 Cable length >50 cm – please specify length in cm

MOUNTING OPTIONS

 $\mathsf{M5}$ rod eye bearing (radial versions), Body Tube Clamp/s (axial or radial versions).

PUSH ROD OPTIONS – standard retained with M5x0.8 female thread, M5 rod eye bearing, Dome end, Sprung loaded (retraction or extension) or Free.



PM Instrumentation | 59 rue Emile Deschanel | F-92400 Courbevoie | France +33(0)1 46 91 93 32 | contact@pm-instrumentation.com | www.pm-instrumentation.com



с

d

е

f

LIPS[®] SERIES P101 Stand-Alone Linear Position Sensor

| | | 4 | 0 | L. | | J | e | • | g | | J | | |
|---|--|--|----------------------|----------|--|---------------------|---------|----------|-------------|--------------|----------|--|--|
| | P101 . | Displacement | Output | Adjustme | ents | Connections | Option | Option | Option | Option | Z-code | | |
| a Displacement (mm) | | | Va | lue | į Z | Z-code | | | | | | | |
| Displacement in mm | e.g. 0 - 254 m | m | | 54 | - | | 412 IEC | 60947-5- | -2 must hav | e options "Y | /" & `J' | | |
| Displacement in mini e.g. 0 - 254 mini | | | | | Connector IP67 M12 IEC 60947-5-2 must have options ۲٬ ۵٬ ۲ Connector IP67 M12 IEC 60947-5-2 must have option ۲٬ | | | | | | | | |
| b Output | | | | | | 0.1% @20°C | | | | | etween | | |
| Supply V dc V _s (tolerance) | c | Dutput | C | ode | 10m | m & 400mm only! | | | | | | | |
| +5V (4.5 - 5.5V) | 0.5 - 4.5V (ratio | ometric with supply) | | Α | | ifies connector wit | | | | | | | |
| ±15V nom. (±9 - 28V) | ±5V | | | | | | | | | | | | |
| +24V nom. (13 - 28V) | 0.5 - 9.5V | | | с | | | | | | | | | |
| ±15V nom. (±13.5 - 28V) | ±10V | | | D | | | | | | | | | |
| +24V nom. (18 - 28V) | 4 - 20mA 2 wi | re | | E | | | | | | | | | |
| +24V nom. (13 - 28V) | 4 - 20mA 3 wi | re Sink | | F | | | | | | | | | |
| +24V nom. (9 - 28V) | 0.5 - 4.5V | | | G | | | | | | | | | |
| +24V nom. (13 - 28V) | | н | | | | | | | | | | | |
| | | | | | | | | | | | | | |
| Calibration Adjust | ments | | C | ode | | | | | | | | | |
| Accessible - default ^{\dagger} | ⁺ Axial body style only. Radial body | | ody bl | ank | | | | | | | | | |
| Sealed | style sealed by | / default. | | Y | | | | | | | | | |
| d Connections Cable* c | or Connector | | C | ode | | | | | | | | | |
| Cable Gland - Radial | IP67 Pg9 | | I | xx | | | | | | | | | |
| Connector - Axial | IP65 DIN 4365 | 50 `C' | | J | | | | | | | | | |
| Connector - Radial | IP67 M12 IEC | 60947-5-2 | | к | | | | | | | | | |
| Cable Gland - Axial | IP67 M12 | | L | xx | | | | | | | | | |
| Cable Gland - Axial IP67 Short | | | | lxx | | | | | | | | | |
| *Supplied with 50 cm as standar specifies cable gland with 20 me | rd, specify required cab etres of cable. Nb: rest | le length specified in o ricted cable pull streng | cm. e.g. L20 jth. | 00 | | | | | | | | | |
| e Body Fittings | | | C | ode | | | | | | | | | |
| None - default | | | bl | ank | | | | | | | | | |
| M5 Rod-eye Bearing | Radial body st | yle only | | N | | | | | | | | | |
| Body Clamps - 1 pair | | | | Р | | | | | | | | | |
| Body Clamps - 2 pairs | | | F | P2 | | | | | | | | | |
| f Sprung Push Rod | | | C | ode | | | | | | | | | |
| None - default | | | bl | ank | | | | | | | | | |
| Spring Extend | Up to 300mm | displacement. | | R | | | | | | | | | |
| Spring Retract | Captive push rod only. | | | s | | | | | | | | | |
| g Push Rod Fittings | | | C | ode | | | | | | | | | |
| None - default | Female Thread | d M5x0.8x9 deep | b bl | ank | | | | | | | | | |
| Dome end | Required for o | ption `R' | | т | | | | | | | | | |
| M5 Rod-eye Bearing | | | | U | | | | | | | | | |
| h Push Rod Options | | | C | ode | | | | | | | | | |
| Captive - default | Push rod is ret | ained | bl | ank | | | | | | | | | |
| Non-captive | Push rod can o | depart body | | v | | | | | | | | | |
| | | | | | | | | | | | | | |

| j Z-code | Code |
|--|------|
| Connector IP67 M12 IEC 60947-5-2 must have options `Y' & `J' | Z600 |
| Connector IP67 M12 IEC 60947-5-2 must have option 'J' | Z601 |
| $\leq \pm 0.1\%$ @20°C Independent Linearity displacement between 10mm & 400mm only! | Z650 |
| Connector with cable $option$ 'J' or 'K' with length required in cm i.e. J100 specifies connector with 100cm of cable. | Z999 |

g

h

j

PM Instrumentation | 59 rue Emile Deschanel | F-92400 Courbevoie | France +33(0)146919332|contact@pm-instrumentation.com|www.pm-instrumentation.com



P101

POSITEK LIMITE

DIN 43650 C

3

IEC 60947-5-2

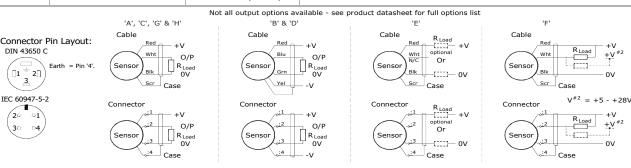
T

01

 $\Box 1$ 2

Installation Information LIPS[®] P101 STAND-ALONE LINEAR POSITION SENSOR

| Output Option Output Description: S | | Supply Voltage: V _s (tolerance) | Load resistance: (include leads for 4 to 20mA O/Ps) | | | |
|--|--------------------------------------|---|---|--|--|--|
| Α | 0.5 - 4.5V (ratiometric with supply) | +5V (4.5 - 5.5V) | ≥ 5kΩ | | | |
| в | ±5V | ±15V nom. (±9 - 28V) | ≥ 5kΩ | | | |
| С | 0.5 - 9.5V | +24V nom. (13 - 28V) | ≥ 5kΩ | | | |
| D | ±10V | ±15V nom. (±13.5 - 28V) | ≥ 5kΩ | | | |
| E | 4 - 20mA 2 wire Current Loop | +24V nom. (18 - 28V) | \approx 0 - 300 max. @24V \sim 1.2 to 6V across 300 _ {R_ max. = (V_s - 18) / 20^3} | | | |
| F | 4 - 20mA 3 wire Sink | +24V nom. (13 - 28V) | $\approx \ 0 \ - \ 950\Omega \ \text{max}. \ @24V \sim 3.8 \ \text{to} \ 19V \ \text{across} \ 950\Omega \{R_L \ \text{max}. \ = \ (V_s \ - \ 5) \ / \ 20^{\cdot 3}\}$ | | | |
| G | 0.5 - 4.5V | +24V nom. (9 - 28V) | ≥ 5kΩ | | | |
| н | 4 - 20mA 3 wire Source | +24V nom. (13 - 28V) | ≈ 0 - 300 Ω max. ~ 1.2 to 6V across 300 Ω | | | |

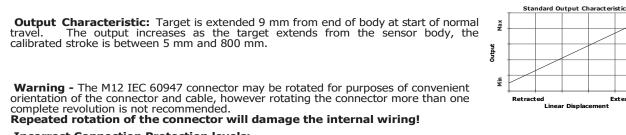


Calibration Adjustmente

00

Gain and Offset Adjustment: (Where accessible - Typically \pm 10% Min available) To adjust the gain or offset use a small potentiometer adjuster or screwdriver 2mm across. Do not apply too much force on the potentiometers.

Mechanical Mounting: Depending on options; Body can be mounted by M5x0.8 male thread, M5 rod eye or by clamping the sensor body - body clamps are available, if not already ordered. Target by M5x0.8 female thread or M5 rod eye. It is assumed that the sensor and target mounting points share a common earth.



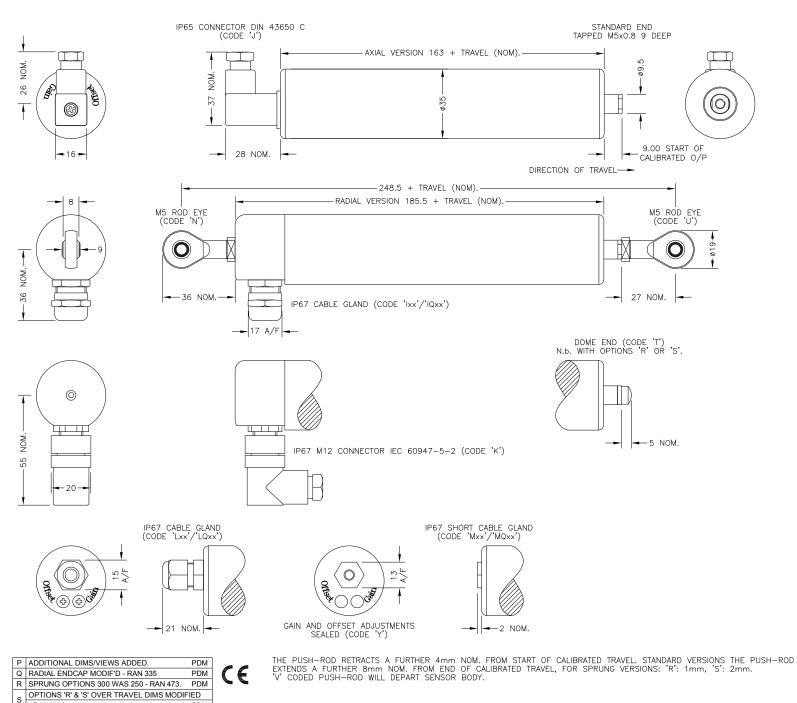
Incorrect Connection Protection levels:-

- **Not protected** the sensor is **not** protected against either reverse polarity or over-voltage. The risk of damage should be minimal where the supply current is limited to less than 50mA. Supply leads diode protected. Output must not be taken outside \pm 12V. Supply leads diode protected. Output must not be taken outside 0 to 12V. Α
- B & D
- C & G
- E, F & H Protected against any misconnection within the rated voltage.

- RAN1030.

T RANGE WAS 50-600mm RAN1056

U RANGE NOTE AMENDED ~ RAN1200



| DUCILER | Ρ | 05/07/11 | + - | CHECKED BY | | | | |
|---------|-----------------|------------------|---|------------|-----------------------|--|--|--|
| LOSITEV | Q | 07/03/13 | $ \oplus \subset $ | RDS | X.X ±0.2 X.XX ±0.1 | | | |
| | R | 08/04/14 | ~ ~ | | DIMS mm | | | |
| | S | 28/07/15 | DESCRIPTION | | | | | |
| | Т | 9/11/15 | P101 LIPS STAND ALONE LINEAR POSITION SENSOR | | | | | |
| | U | 29/08/17 | | | | | | |
| | | | | | | | | |
| | scale 12.5mm | | DRAWING F | P101-11 | REV U | | | |
| LIMITED | + | <u>< ></u> | | SHEE | T 1 0F 1 | | | |

OUTPUT

0.5 TO 9.5V

0.5 TO 4.5V

3-CORE: JACKET Ø4mm 4-CORE: JACKET Ø4.6mm

RED

GREEN

YELLOW

BLUE

IN INCREMENTS OF 1mm.

BODY MATERIAL: STAINLESS STEEL.

SINGLE PAIR OF BODY CLAMPS 'P'

TWO PAIRS OF BODY CLAMPS 'P2'

SPRING RETURN PUSH-ROD, TRAVEL ≤300mm

RETURN TO RETRACTED POSITION (CODE 'S') PUSH-ROD FREE (CODE 'V') - NOT AVAILABLE WITH

GAIN AND OFFSET ADJUSTMENTS NOT AVAILABLE WITH

50 100 200 250 300

STROKE (mm) SPRING FORCE V STROKE

(CODE 'R' OR 'S')

RETURN TO EXTENDED POSITION (CODE 'R'

RADIAL BODY, CODE 'Ixx' AND 'K', OPTIONS.

3 CORE 4 CORE

SCREEN SCREEN

FURTHER OPTIONS:

20

Б

0

Ê

FORCE 10

RFD

BLACK

WHITE

4 TO 20mA 2-WIRE

CABLE/CONNECTOR* CONNECTIONS;

4 TO 20mA 3-WIRE SINK

4 TO 20mA 3-WIRE SOURCE

±5V

±10V

0.5 TO 4.5V RATIOMETRIC

SUPPLY CURRENT 12mA TYP. 20mA MAX.

SINK VERSION OUTPUT COMPLIANCE 5-28V

+Ve

ΟV

*CONNECTORS: MAXIMUM CONDUCTOR CROSS SECTION 0.75mm²

RANGE OF DISPLACEMENT FROM 0-5mm TO 0-800mm e.g.76,

OUTPUT

SOURCE VERSION DRIVE 3000 MAX TO OV CABLE: 0.2mm², O/A SCREEN, PUR JACKET - SUPPLIED WITH 50cm OR REQUIRED LENGTH IN cm. e.g. 'L50'

CONNECTOR

:1

:3

:4

:2

:4

A

SUPPLY

STANDARD

> BUFFERED

5V

24V

24V

24V

24V

-Ve - OPTIONS: B OR D

SPRUNG OPTIONS.

'S'

'R

BODY - OPTIONS: A, C, E-H

24V

±15V

±15V

DRAWINGS NOT TO BE CHANGED WITHOUT REFERENCE TO THE CHANGE PROCEDURE. CHANGES TO PARTS USED IN INTRINSICALLY SAFE PRODUCT MUST BE APPROVED BY THE AUTHORISED PERSON THIS IS AN UNCONTROLLED PRINT AND WILL NOT BE UPDATED.

PDM

RDS

PDM