

F6D80-40 100N/10Nm/MP11



Description

The multi-component sensor F6D80 is used for force and torque measurement in three mutually perpendicular axes.

The multi-component sensor F6D80 is equipped with fastening flanges according to DIN EN ISO 9409-1 for industrial robots. The measuring flange of the sensor contains tapped holes M6 on the same pitch circle. The F6D force / torque sensor can be mounted to the robot flange without additional adapters, making it particularly flat and light compared to the K6D series sensors.

The evaluation of the force and moment load is carried out with an external measuring amplifier GSV-8DS SubD44HD or GSV-8AS.

The sensors are made of an aluminum alloy.

Our robotics partner IPR offers solutions for applications of force / torque sensors.

Technical Data

Force sensor

Type	6-Axis force sensor
Force direction	Tension / Compression
Rated force Fx	100 N
Rated force Fy	100 N
Rated force Fz	200 N
Force introduction	Inner thread
Dimension 1	4xM6
Sensor Fastening	Through bore
Operating force	300 %FS
Rated displacement	0.05 mm
Twist	0.04 rad
Material	Aluminium alloy
Height	40 mm
Length or Diameter	80 mm
Rated torque Mx	10 Nm
Rated torque My	10 Nm
Rated torque Mz	10 Nm
Breaking force	600 %FS

Electrical Data

Input resistance	1000 Ohm
Tolerance input resistance	50 Ohm
Output resistance	1000 Ohm
Tolerance output resistance	50 Ohm
Insulation resistance	2 GOhm
Rated range of excitation voltage f	2.5 ... 5 V
Operating range of excitation voltage f	1 ... 10 V
Zero signal	1 mV/V
Rated output	0.4 mV/V / FS

Precision

Accuracy class	1%
Relative linearity error	0.1 %FS
Relative zero signal hysteresis	0.1 %FS
Temperature effect on zero signal	0.1 %FS/K
Temperature effect on characteristic value	0.05 %RD/K
Relative creep	0.1 %FS
Relative repeatability error	0.5 %FS

Connection Data

Connection type	Connector
Name of the connection	round plug connector MP11, 24-pole, male

Temperature

Rated temperature range f	-10 ... 70 °C
Operating temperature range f	-10 ... 85 °C
Storage temperature range f	-10 ... 85 °C
Environmental protection	IP64

Abbreviation : RD: „Reading“; FS: „Full Scale“;

The application of a calibration matrix is required for the determination of the forces F_x , F_y , F_z and moments M_x , M_y , and M_z from the 6 measurement channels, and to compensate for the crosstalk.

The calibration data are individually determined and documented for the sensor.

The measurement error is expressed individually by the specification of the extended measurement uncertainty ($k = 2$) for the forces F_x , F_y , F_z , and moments M_x , M_y , M_z .

Pin Configuration

Channel	Symbol	Description	Wire colour	PIN
1	+Us	positive bridge supply	red	1
	-Us	negative bridge supply	black	2
	+Ud	positive bridge output	green	3
	-Ud	negative bridge output	white	4
2	+Us	positive bridge supply	blue	5
	-Us	negative bridge supply	yellow	6
	+Ud	positive bridge output	purple	7
	-Ud	negative bridge output	grey	8
3	+Us	positive bridge supply	orange	9
	-Us	negative bridge supply	brown	10
	+Ud	positive bridge output	pink	11
	-Ud	negative bridge output	transparent	12
4	+Us	positive bridge supply	green-black	13
	-Us	negative bridge supply	black-white	14
	+Ud	positive bridge output	red-black	15
	-Ud	negative bridge output	white-black	16
5	+Us	positive bridge supply	purple-black	17
	-Us	negative bridge supply	yellow-black	18
	+Ud	positive bridge output	bue-black	19
	-Ud	negative bridge output	gray-black	20
6	+Us	positive bridge supply	pink-black	21
	-Us	negative bridge supply	brown-black	22
	+Ud	positive bridge output	orange-black	23
	-Ud	negative bridge output	transparent-black	24

Shield: connected with sensor housing;

Manual

Stiffness matrix F6D80-40 100N/10Nm

36.6 kN/mm	0.0	0.0	0.0	348 kN	0.0	u_x
0.0	36.6 kN/mm	0.0	-348 kN	0.0	0.0	u_y
0.0	0.0	357.9 kN/mm	0.0	0.0	0.0	u_z
0.0	-348 kN	0.0	199.0 kNm	0.0	0.0	ϕ_x
348 kN	0.0	0.0	0.0	199.0 kNm	0.0	ϕ_y
0.0	0.0	0.0	0.0	0.0	63.1 kNm	ϕ_z

Element	Description of the context
[kN/mm]	force- displacement
[kNm]	torque- twist
[kN]	force- twist and torque- displacement

Mounting

Calibration matrix

The calibration matrix contains 36 calibration factors for calculating the forces and torques from the 6 output signals of the force sensor. A Labview vi is available for processing the calibration matrix

Measuring amplifier

The measuring amplifier GSV-8DS or GSV-8AS has 24-pole plug connector to connect the 6-axis force/torque sensor. The mechanical forces and torques are calculated from 6 output voltages of each measuring channel with the calibration matrix.

Software

The GSVmulti software is included in delivery with measuring amplifiers GSV-8. The software allows the application of the calibration matrix and the displacement of the coordinate system to represent the torques around a freely selectable reference point.

To create your own software, a Labview VI is available.

Mounting instruction

The force is applied to a circular ring (Ø80-Ø40) on the live end of the sensor. The area inside the circular ring remains unloaded.

A center hole Ø6 serves to secure the angular position.

4x M6 external thread for mounting on robot flange (mounted with Allen key from the tool side, the screws are integrated in the F6D sensor, can not be lost);

4x M6 internal thread for mounting the tool (this flange corresponds again to the robot flange);

Summary: The sensor has M6 internal thread and M6 external thread.

Robotics solutions from IPR


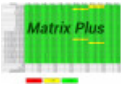








Our robotics partner IPR offers solutions for applications of force / torque sensors in the areas of

- Mounting and handling technology
- Machine loading
- Foundry and blacksmith
- Cavity preservation
- Sealing and damping
- Lack and paint
- Services

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accessories

Description	Description
 <p>K6D-CalibrationMatrix SL</p>	Standard calibration matrix "Small load" for the sensors with small measuring ranges
 <p>K6D-CalibrationMatrix SL/Plus</p>	High accuracy calibration matrix for 6-axis force/torque sensors;
 <p>GSV-8DS</p>	8-channel amplifier with USB port, analog output, UART interface. Other versions GSV-8AS CAN with Canbus and GSV-8AS EC with EtherCAT fieldbus.
 <p>GSV-8AS</p>	8-channel amplifier with USB port, analog output, 16x DIO, UART interface.
 <p>Connection cable MP11/f-D-Sub44HD/m</p>	Connection cable for connecting the K6D sensor to an 8-channel measuring amplifier GSV-8DS SubD44HD
 <p>Connection cable MP11/f-D-Sub44HD/m/straight</p>	Straight connection cable for connecting the K6D sensor to an 8-channel measuring amplifier GSV-8DS SubD44HD
 <p>Connection cable MP11/f-D-Sub44HD/m/angled</p>	Angled connection cable for connecting the K6D sensor to an 8-channel measuring amplifier GSV-8DS SubD44HD
 <p>Connection cable MP11/f-open end</p>	Connection cable for K6D sensor
 <p>Connection cable MP11/f-M16/24p/m</p>	Connection cable for the K6D sensor to 8-channel measuring amplifier GSV-8AS
 <p>Connection cable MP11/f-M16/24p/m/angled</p>	Angled connection cable for the K6D sensor to 8-channel measuring amplifier GSV-8AS