



## P130 LONG STROKE IN-CYLINDER LINEAR POSITION SENSOR High-resolution position feedback for hydraulic and pneumatic cylinders

- Non-contacting inductive technology to eliminate wear
- Travel set to customer's requirement
- Compact and self-contained
- High durability and reliability
- High accuracy and stability
- Sealing to IP65/IP67 as required

As a leading designer and manufacturer of linear, rotary, tilt and intrinsically safe position sensors, Positek® has the expertise to supply a sensor to suit a wide variety of applications.

Our P130 is an affordable, durable, highaccuracy position sensor designed for demanding hydraulic or pneumatic cylinder position feedback applications where service life, environmental resistance and cost are important. particularly suitable for OEMs seeking good sensor performance for arduous applications such as industrial machinery.

Overall performance, repeatability and stability are outstanding over a wide temperature range. The unit is highly compact and space-efficient, being responsive along almost its entire length. Like all Positek® sensors it provides a linear output proportional to travel. Each unit is supplied with the output calibrated to the travel required by the customer, any stroke from 0-400mm to 0-1485mm and with full EMC protection built in.

The sensor is very rugged, being made of stainless steel with an inert fluoropolymersheathed probe with the option of either an aluminium or stainless steel target tube. sensor is easy to install in cylinders and has a wide range of mechanical and electrical options. Environmental sealing is to IP65 or IP67 depending on selected cable or connector options.



#### **SPECIFICATION**

**Dimensions** 

35 mm Body diameter Body Length (to seal face)

How Length (to seal face)

How Length (from seal face)

Target Tube Length

For full mechanical details see drawing P130-11

Independent Linearity

Shift (1980)

And Mark Standard, 48 mm buffered

All mark standard, 48 mm buffered

A

Independent Linearity

< ± 0.01%/°C Gain & **Temperature Coefficients** 

< ± 0.01%FS/°C Offset
> 10 kHz (-3dB)
> 300 Hz (-3dB) 2 wire 4 to 20 mA **Frequency Response** 

Resolution Infinite < 0.02% FSO **Environmental Temperature Limits** 

-40°C to +125°C standard -20°C to +85°C buffered -40°C to +125°C Operating Storage

IP65/IP67 depending on connector / cable option Sealing

**Hydraulic Pressure EMC Performance** EN 61000-6-2, EN 61000-6-3 10 g 40 g Vibration (Electronics) IEC 68-2-6: IEC 68-2-29: Shock (Electronics) 350,000 hrs 40°C Gf

**Drawing List** 

**MTBF** 

Sensor Outline & P130-11

Typical Target Installation details

P100-15 Mounting Thread details

Drawings, in AutoCAD® dwg or dxf format, available on request.

Do you need a position sensor made to order to suit a particular installation requirement or specification? We'll be happy to modify any of our designs to suit your needs please contact us with your requirements.

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## How Positek's technology eliminates wear for longer life

Positek's Inductive technology is a major advance in displacement sensor design. Our displacement transducers have the simplicity of a potentiometer with the life of an LVDT/RVDT.

Our technology combines the best in fundamental inductive principles with advanced micro-electronic integrated circuit technology. A Positek sensor, based on simple inductive coils using Positek's ASIC control technology, directly measures absolute position giving a DC analogue output signal. Because there is no contact between moving electrical components, reliability is high and wear is eliminated for an exceptionally long life.

Our technology overcomes the drawbacks of LVDT technology – bulky coils, poor length-to-stroke ratio and the need for special magnetic materials. It requires no separate signal conditioning.

We also offer a range of ATEX-qualified intrinsicallysafe sensors.

#### **TABLE OF OPTIONS**

**CALIBRATED TRAVEL:** Factory set to any length from 0-400mm to 0-1485mm (e.g. 508mm)

#### **ELECTRICAL INTERFACE OPTIONS**

OUTPUT SIGNAL	SUPPLY INPUT	OUTPUT LOAD		
Standard:				
0.5-4.5V dc ratiometric	$+5V$ dc nom. $\pm$ 0.5V.	5kΩ min.		
Buffered:				
0.5-4.5V dc	+24V dc nom. + 9-28V.	5kΩ min.		
±5V dc	±15V dc nom. ± 9-28V.	5kΩ min.		
0.5-9.5V dc	+24V dc nom. + 13-28V.	5kΩ min.		
±10V dc	±15 V dc nom. ± 13.5-28V.	5kΩ min.		
Supply Current	10mA typical, 20mA maximum.			
4-20mA (2 wire)	+24 V dc nom. + 18-28V.	300Ω @ 24V.		
(3 wire sink)	+24 V dc nom. + 13-28V.	950Ω @ 24V.		
(3 wire source)	+24 V dc nom. + 13-28V.	$300\Omega$ max.		
Sensors supplied with access to output 'zero' and 'span' calibration				

Sensors supplied with access to output 'zero' and 'span' calibration adjustments as standard. No access option available.

#### **CONNECTOR/CABLE OPTIONS**

Connector - Hirschmann GD series IP65
Cable with M12 gland or short gland IP67
Cable length >50 cm – please specify length in cm

#### **MOUNTING THREAD OPTIONS**

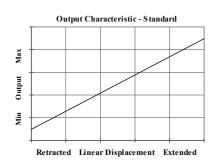
M18, M20, ¾ UNF 30 mm hex A/F, Ø 30 mm seal face. Supplied with O-ring seal.

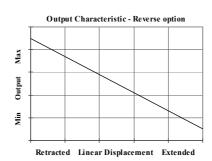
#### **TARGET TUBE**

Stainless Steel (316) OD: 9.45 mm install in 12.7 min bore.

#### **FLANGE OPTIONS**

'Circlip Fit' style
' Screw Fit' style



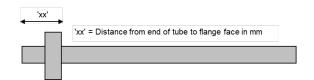


For further information please contact: www.positek.com sales@positek.com

## P130 In-Cylinder Linear Position Sensor



a <b>Displacement</b> (mm)		Value	
Displacement in mm	e.g. 0 - 254 mm	254	
h Outrut			
b <b>Output</b> Supply V dc			
V <sub>s</sub> (tolerance)	Output	Code	
+5V (4.5 - 5.5V)	0.5 - 4.5V (ratiometric with supply)	A	
±15V nom. (±9 - 28V)	±5V	В	
+24V nom. (13 - 28V)	0.5 - 9.5V	С	
±15V nom. (±13.5 - 28V)	±10V	D	
+24V nom. (18 - 28V)	4 - 20mA 2 wire	E	
+24V nom. (13 - 28V)	4 - 20mA 3 wire Sink	F	
+24V nom. (9 - 28V)	0.5 - 4.5V	G	
+24V nom. (13 - 28V)	4 - 20mA 3 wire Source	Н	
c Calibration Adjust	ments	Code	
Accessible - default		blank	
Sealed		Y	
d Connections Cable o	r Connector	Code	
Connector	IP65 DIN 43650 'C'	J	
Connector	pre wired	Jxx	
Cable Gland	IP67 nylon	Lxx	
Cable Gland <sup>†</sup>	IP67 Short	Mxx	
Specify required cable length 'x 50 cm supplied as standard. †Nb	x' in cm. e.g. L2000 specifies cable gland with 20 p: restricted cable pull strength.	m of cable,	
e <b>Mounting Thread</b>		Code	
M20 x 1.5	Hex. 30 mm A/F, Ø 30 mm seal	N	
3/4 16 UNF	face.	P	
M18 x 1.5	Supplied with O-ring seal.	T	
See P100-15 Drawing for Mating	g Thread Details.		
f Target Tube Moun	ting Flange	Code	
Ø19x6 Circlip retained	Please specify flange position in mm.	Vxx	
Equivalent to MTS 201542 Magnet	eg. W17.5 specifies a MTS style flange fitted 17.5 mm from the	Wxx	
See XXXX-11 Drawing for Targe See P130-12 Drawing for Typica			
g <b>Z-code</b>		Code	
Connector IP67 M12 IEC 60176-2-101 must have options 'Y' & 'J'			
Connector IP67 M12 IEC 60176-2-101 must have option 'J' <b>Z601</b>			

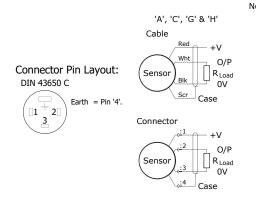


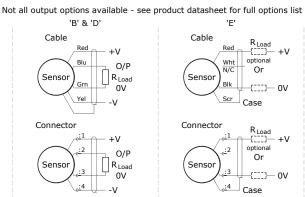


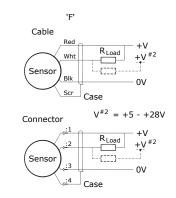
## **Installation Information**

## P130 LONG STROKE IN-CYLINDER LINEAR POSITION SENSOR

Output Option	Output Description:	Supply Voltage: V <sub>s</sub> (tolerance)	<b>Load resistance:</b> (include leads for 4 to 20mA O/Ps)
Α	0.5 - 4.5V (ratiometric with supply)	+5V (4.5 - 5.5V)	≥ 5kΩ
В	±5V	±15V nom. (±9 - 28V)	≥ 5kΩ
С	0.5 - 9.5V	+24V nom. (13 - 28V)	≥ 5kΩ
D	±10V	±15V nom. (±13.5 - 28V)	≥ 5kΩ
E	4 - 20mA 2 wire Current Loop	+24V nom. (18 - 28V)	$\approx 0$ - $300\Omega$ max. @24V $\sim 1.2$ to 6V across $300\Omega$ $~\{R_L$ max. = (V_s - 18) / $20^{\cdot 3}\}$
F	4 - 20mA 3 wire Sink	+24V nom. (13 - 28V)	$\approx 0$ - $950\Omega$ max. @24V $\sim 3.8$ to 19V across $950\Omega$ $~\{R_L \; max. = (V_s - 5) \; / \; 20^{\cdot 3}\}$
G	0.5 - 4.5V	+24V nom. (9 - 28V)	≥ 5kΩ
Н	4 - 20mA 3 wire Source	+24V nom. (13 - 28V)	$\approx$ 0 - 300Ω max. $\sim$ 1.2 to 6V across 300Ω







Calibration

Adjustments

0 0

**Gain and Offset Adjustment:** (Where accessible - Typically ± 10% Min available) To adjust the gain or offset use a small potentiometer adjuster or screwdriver 2mm across. Do not apply too much force on the potentiometers.

**Mechanical Mounting:** Via mounting thread, maximum tightening torque: 100Nm. See drawing P100-15, Installation Details Mounting Threads & Seals. An O ring seal is provided, size BS908 for M20 & 3/4 UNF thread or 14.3 x 2.4 for M18 thread. Install the target tube using the flange provided to fix into the piston rod. The target tube is intended to have some lateral freedom of movement to allow for misalignments in the assembly. The end of the target tube can be proud or flush with the piston end face as required. It is assumed that the sensor and target mounting points share a common earth.

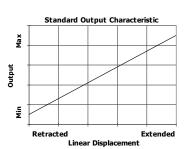
Output Characteristic: Target position at start of normal travel is 36.0 mm from seal The output increases as the target is moved away from the sensor body, the calibrated stroke is between 400 mm and 1485 mm.

#### **Incorrect Connection Protection levels:-**

**Not protected** – the sensor is **not** protected against either reverse polarity or over-voltage. The risk of damage should be minimal where the

supply current is limited to less than 50mA. Supply leads diode protected. Output must not be taken outside  $\pm$  12V.

B & D C & G Supply leads diode protected. Output must not be taken outside 0 to 12V. E, F & H Protected against any misconnection within the rated voltage.



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P130-19c